ON THE MEASURE OF INTERSECTION OF CYLINDERS

BY

S. Alesker*

School of Mathematical Sciences, Tel Aviv University
Tel Aviv 69978, Israel
e-mail: semyon@math.tau.ac.il

ABSTRACT

In this paper we study an extremal problem on the minimum of the measure of intersection of cylinders satisfying certain geometric conditions. The main result generalizes previous results of Khatri, Sidak and Gluskin to the wider class of all rotation invariant measures.

Let rD_k denote the k-dimensional disk of radius r in the Euclidean space \mathbb{R}^n , i.e. D_k is a centered unit Euclidean ball in some k-dimensional linear subspace. By a **rounded cylinder** we will call a set of the form $rD_k \times \mathbb{R}^{n-k}$, where \mathbb{R}^{n-k} is orthogonal to D_k . Let O(n) denote the orthogonal group in \mathbb{R}^n . We call two linear subspaces $M, N \subset \mathbb{R}^n$ pairwise orthogonal in the following sense: if $\dim M + \dim N \leq n$ then M and N are pairwise orthogonal in the usual sense; if $\dim M + \dim N \geq n$ then M and N span all the space \mathbb{R}^n and $(M \ominus (M \cap N))$ is orthogonal to $(N \ominus (M \cap N))$ in the usual sense.

The main results of this paper are Theorems 1 and 2 below.

THEOREM 1: Let μ be a nonnegative rotation invariant measure on \mathbb{R}^n . Let T_1 be a rounded cylinder

$$T_1 = rD \times E$$
,

where $E \subset \mathbb{R}^n$ is a linear subspace and $D \subset E^{\perp}$ is the unit Euclidean ball in E^{\perp} . Let T_2 be a (not rounded) cylinder of the form

$$T_2 = \Omega \times F$$
,

Partially supported by a Minkowski Center grant.
 Received February 1, 1998

where $F \subset \mathbb{R}^n$ is a linear subspace and $\Omega \subset F^{\perp}$ is a centrally symmetric convex body.

Then

$$\min_{U \in O(n)} \mu(U(T_1) \cap T_2)$$

is achieved when the subspaces span(UD) and span Ω are pairwise orthogonal in the above sense.

THEOREM 2: Let T_1, \ldots, T_s be rounded cylinders,

$$T_i = r_i D_{k_i} \times \mathbb{R}^{n-k_i},$$

such that $\sum_{i=1}^{s} k_i \leq n$. Let μ be any nonnegative measure on \mathbb{R}^n . Then

$$\min_{U_i \in O(n)} \mu \Big(\bigcap_{1}^s U_i(T_i) \Big)$$

is achieved when all $U_i(T_i)$ are pairwise orthogonal, more precisely span $U_i(D_{k_i})$ is orthogonal to span $U_j(D_{k_j})$, $i \neq j$.

Remarks: (1) Theorem 2 generalizes the previous results of Khatri [7], Sidak [9] and Gluskin [3], [4]. It follows from [7], [9], [3] that Theorem 2 is true when all cylinders are strips (i.e. $T_i = [-r_i, r_i] \times \mathbb{R}^{n-1}$) and the measure μ is, in addition, absolutely continuous with respect to the Lebesgue measure with radial decreasing density. Theorem 2 for arbitrary cylinders follows directly from the argument of [4] in the case when μ is the standard Gaussian measure.

- (2) A new interesting special case of Theorem 2 is when the measure μ is the Lebesgue measure concentrated on the Euclidean sphere.
- (3) Some geometric properties of the intersection of the projective caps (i.e. complements to the strips) on the sphere were studied by Litvak, Milman and Schechtman [8], where applications to the asymptotic theory of Banach spaces can be found.
- (4) For the related results on the volume of intersection of caps on the sphere, see the paper by Gromov [5].

Assuming Theorem 1 let us prove Theorem 2.

Proof of Theorem 2: One can easily see that the intersection of the first (s-1) cylinders $T_1 \cap \cdots \cap T_{s-1}$ has the form $\Omega \times N_{k_s}$, where N_{k_s} is a linear subspace of dimension dim $N_{k_s} = k_s$ and Ω is a centrally symmetric convex set contained in the orthogonal complement $N_{k_s}^{\perp}$.

By Theorem 1, $\min_{U \in O(n)} \mu((\Omega \times N_{k_s}) \cap UT_s)$ is achieved when UD_{k_s} is contained in N_{k_s} . Then an easy induction in s finishes the proof.

Theorem 2 applied to the Lebesgue measure on the unit sphere implies easily the following result (however, as pointed out to us by B. Sudakov and the referee, it has a direct simpler proof).

COROLLARY 3: Let E_1, \ldots, E_s be linear subspaces of the real (complex) n-dimensional Euclidean (Hermitian) space such that $\sum_{i=1}^{s} \dim(E_i) = n$. Let w_1, \ldots, w_s be nonnegative numbers with $\sum_{i=1}^{s} w_i^2 = 1$. Then there exists a vector y from the unit sphere, ||y|| = 1, such that

$$\|\operatorname{Pr}_{E_i} y\| \leq w_i \quad \text{for all } i = 1, \dots, s,$$

where Pr_E denotes the orthogonal projection onto the subspace E.

In particular, if x_1, \ldots, x_n are vectors with $||x_i|| = 1$ and w_1, \ldots, w_n are non-negative numbers with $\sum_{i=1}^{n} w_i^2 = 1$, then there exists y_i , $||y_i|| = 1$, such that

$$|\langle y, x_i \rangle| \le w_i$$
 for all $i = 1, \dots, n$,

where $\langle \cdot, \cdot \rangle$ is the inner product.

Before proving Theorem 1 we will state the following lemma (which is essentially well-known).

LEMMA: Let $k \geq 1$. Let E_0, E be k-dimensional subspaces of the Euclidean space \mathbb{R}^{2k} . Write $\mathbb{R}^{2k} = E_0 \oplus E_0^{\perp}$.

Then there exists an operator

$$V: E_0 \longrightarrow E_0^{\perp}$$

such that $||V|| \leq \pi/2$ and

$$E = \exp\begin{pmatrix} 0 & -V^* \\ V & 0 \end{pmatrix} E_0.$$

Proof (Compare [6], Ch. I, §1, Theorem 1): Consider the restriction to E of the orthogonal projection onto E_0 :

$$P: E \longrightarrow E_0$$
.

By the general fact of operator theory, there exists an orthonormal basis x_1, \ldots, x_k in E_0 and orthonormal basis y_1, \ldots, y_k in E such that

$$Py_i = s_i x_i$$
 for every i ,

where s_i are the singular numbers of P, hence $0 \le s_i \le 1$. Let us choose a unit vector x_i' in the span of x_i, y_i to be orthogonal to x_i . Then easily $x_1, x_1', \ldots, x_k, x_k'$ form an orthonormal basis in \mathbb{R}^{2k} .

Put $\cos \beta_i := s_i$, $0 \le \beta_i \le \pi/2$.

Let us define operator $V: E_0 \longrightarrow E_0^{\perp}$ as

$$Vx_i = \beta_i x_i'.$$

Then easily V satisfies the lemma.

Remark: In fact, the curves of the form

$$\exp t \cdot \begin{pmatrix} 0 & -V^* \\ V & 0 \end{pmatrix} E_0$$

are geodesics in the Grassmannian $Gr_{2k,k}$ and every geodesic through E_0 has such a form (see e.g. [1], Corollary 3.33(2)). But we will not use this property.

Proof of Theorem 1: Let us prove the theorem when the measure μ is the Lebesgue measure concentrated on the unit sphere S^{n-1} , since the general case follows immediately by integration in polar coordinates.

Passing if necessary to smaller n and using Fubini's theorem, we may assume that $\dim D + \dim \Omega \geq n$. We may and will also assume that D and Ω are in generic position, namely if

$$L := \operatorname{span} D \cap \operatorname{span} \Omega$$
,

then $\dim L = \dim(\operatorname{span} D) + \dim(\operatorname{span} \Omega) - n$.

Consider another rounded cylinder

$$T = r\tilde{D} \times G,$$

where \tilde{D} is the unit ball in the linear space G^{\perp} (so that span $\tilde{D} = G^{\perp}$),

$$\dim \tilde{D} = \dim D,$$

span
$$\tilde{D} \supset L$$
,

and span \tilde{D} is orthogonal to span Ω in the sense mentioned at the beginning of the paper. We want to prove that

$$\mu(T\cap T_2)\leq \mu(T_1\cap T_2).$$

Next we observe that the case $\dim D > \dim \Omega$ can be easily reduced to the case $\dim D \leq \dim \Omega$ by lowering the dimension of the total space. Indeed, set

$$H=(\operatorname{span}\tilde{D})\cap(\operatorname{span}D),$$

$$J = (\operatorname{span} \tilde{D}) \ominus H.$$

Easily dim $J + \dim L < \dim(\operatorname{span} \tilde{D})$. Then

$$V := (\operatorname{span} \tilde{D}) \ominus (L \oplus J)$$

is non-trivial, $V \perp \operatorname{span} \Omega$, and $V \subset H$. Then

$$\mathbb{R}^n = (\operatorname{span} \Omega \oplus J) \oplus V.$$

Using Fubini's theorem for sections of S^{n-1} parallel to $(\operatorname{span} \Omega \oplus J)$ we see that the case $\dim D > \dim \Omega$ is reduced to the case $\dim D \leq \dim \Omega$. So let us assume that

$$\dim D \leq \dim \Omega$$
.

Note that since D and Ω are assumed to be in generic position, then

$$L = (\operatorname{span} D) \cap (\operatorname{span} \Omega) = (\operatorname{span} \tilde{D}) \cap (\operatorname{span} \Omega).$$

Let $\Gamma = (\operatorname{span} \tilde{D}) \ominus L$. By the trivial linear algebra argument one can decompose $\operatorname{span} \Omega$ into an orthogonal direct sum

$$\operatorname{span}\Omega=L\oplus M\oplus \Delta,$$

where $\dim \Delta = \dim \Gamma$, $L \oplus \Delta \oplus \Gamma \supset \operatorname{span} D$, and M is just an orthogonal complement of $L \oplus \Delta$ inside $\operatorname{span} \Omega$. Thus

(1)
$$\mathbb{R}^n = L \oplus M \oplus \Delta \oplus \Gamma,$$

$$(2) \hspace{1cm} \Omega \subset L \oplus M \oplus \Delta \oplus \{0\} \hspace{0.2cm} \text{and} \hspace{0.2cm} T \subset L \oplus \{0\} \oplus \{0\} \oplus \Gamma.$$

Using Lemma 4 one can find an operator

$$V: \Gamma \longrightarrow \Delta$$

such that

$$||V|| \le \frac{\pi}{2},$$

(4)
$$\exp\left(\frac{0 + 0}{0 + 0} \right) (\operatorname{span} \tilde{D}) = \operatorname{span} D.$$

Consider a one-parametric group of orthogonal operators A_t : $\mathbb{R}^n \longrightarrow \mathbb{R}^n$, $0 \le t \le 1$, defined by

(5)
$$A_t = \exp t \cdot \begin{pmatrix} 0 & 0 \\ 0 & 0 & V \\ -V^* & 0 \end{pmatrix}.$$

In particular, A_t acts as the identity operator on $L \oplus M$ for all t. Clearly $A_0 = \operatorname{Id}_n$ and $A_1 T = T_1$. To prove Theorem 1 it suffices to show that

$$\operatorname{mes}(S^{n-1} \cap A_t T \cap (\Omega \times F))$$

increases in $t \in [0,1]$, where mes denotes the Lebesgue measure concentrated on the unit sphere S^{n-1} (recall that $T_2 = \Omega \times F$).

First recall that a characteristic (indicator) function of every compact convex centrally symmetric set Ω can be approximated a.e. and in the L_1 -norm by a smooth log-concave even function (to see this consider the convolution

$$f_{\varepsilon} = \mathbf{1}_{\Omega} * \left(\frac{1}{(\sqrt{2\pi\varepsilon})^n} e^{-|x/\varepsilon|^2/2} \right),$$

where $1\!\!1_{\Omega}$ is the characteristic function of Ω , $\varepsilon \to +0$. Then f_{ε} is a log-concave function by the Prekopa–Leindler inequality as a convolution of two log-concave functions, and $f_{\varepsilon} \to 1\!\!1_{\Omega}$ a.e. and in L_1 -norm). In our case $\Omega \subset L \oplus M \oplus \Delta \oplus \{0\}$, hence taking the above convolution with respect to this subspace we may assume that for $p = (X_1, X_2, Y, Z)$, $f_{\varepsilon}(p) = f_{\varepsilon}(X_1, X_2, Y)$ (where the coordinates correspond to the decomposition (1)). It is easy to see that if we restrict all the functions onto the unit sphere $S^{n-1} \subset \mathbb{R}^n$, then $f_{\varepsilon}|_{S^{n-1}} \longrightarrow 1\!\!1_{\Omega}|_{S^{n-1}}$ a.e. and in $L_1(S^{n-1})$. Hence in order to prove the theorem it is sufficient to show that if $f(p) = f(X_1, X_2, Y)$ is a smooth log-concave even function, then (setting $T' := T \cap S^{n-1}$)

$$\varphi(t) := \int_{A \cdot T'} f(p) dp, \quad 0 \le t \le 1$$

is an increasing function of t.

One can easily check the following formula (since A_t are measure preserving):

(6)
$$\frac{d}{dt}\varphi(t) = \frac{d}{dt}\int_{T'} f(A_t p) dp = \int_{\partial T'} f(A_t p) \langle n(p), v(p, t) \rangle dp,$$

where ∂T ($\subset S^{n-1}$) is the boundary of T', n(p) is the unique *inner* normal to $\partial T'$ at $p \in \partial T'$ (in particular, n(p) is a tangent vector to S^{n-1} at p), and

$$v(p,t) = \frac{d}{dt}A_t p$$

is the vector of velocity at point p at time t.

Clearly,

$$(7) \ \partial T' = \{(X_1, X_2, Y, Z) \in S^{n-1} \Big| |X_1|^2 + |Z|^2 = r^2\} = \sqrt{1 - r^2} S_{X_2, Y} \times r S_{X_1, Z}$$

where $|\cdot|$ denotes the Euclidean norm, $S_{X_1,Z}$ is the unit sphere in $L \oplus \Gamma$, and $S_{X_2,Y}$ is the unit sphere in $M \oplus \Delta$. We may assume r < 1. Then a direct elementary computation shows that, at $p = (X_1, X_2, Y, Z) \in \partial T'$,

(8)
$$n(p) = \left(-\frac{\sqrt{1-r^2}}{r}X_1, \frac{r}{\sqrt{1-r^2}}X_2, \frac{r}{\sqrt{1-r^2}}Y, -\frac{\sqrt{1-r^2}}{r}Z\right).$$

Since

$$\frac{d}{dt}A_t = \begin{pmatrix} 0 & 0 & 0\\ 0 & 0 & V\\ -V^* & 0 \end{pmatrix} \cdot A_t,$$

then obviously

(9)
$$v(p,t) = (0,0,VZ,-V^*Y).$$

Substituting (7), (8), (9) into (6) we obtain

$$\frac{d}{dt}\varphi(t) = \int_{\partial T'} f(A_t p) \left[\frac{r}{\sqrt{1 - r^2}} \langle Y, VZ \rangle + \frac{\sqrt{1 - r^2}}{r} \langle Z, V^*Y \rangle \right]
= \frac{1}{r\sqrt{1 - r^2}} \int_{rS_{X_1, Z}} dX_1 dZ \int_{\sqrt{1 - r^2}S_{X_2, Y}} dX_2 dY f(A_t p) \langle Y, VZ \rangle.$$

Let us compute A_t . First

$$\exp\begin{pmatrix} 0 & V \\ -V^* & 0 \end{pmatrix} = \sum_{k=0}^{\infty} \frac{1}{k!} \begin{pmatrix} 0 & V \\ -V^* & 0 \end{pmatrix}^k$$
$$= \sum_{j=0}^{\infty} \left[\frac{1}{(2j)!} \begin{pmatrix} 0 & V \\ -V^* & 0 \end{pmatrix}^{2j} + \frac{1}{(2j+1)!} \begin{pmatrix} 0 & V \\ -V^* & 0 \end{pmatrix}^{2j+1} \right].$$

Since

$$\left(\begin{array}{cc} 0 & V \\ -V^* & 0 \end{array} \right)^2 = - \left(\begin{array}{cc} VV^* & 0 \\ 0 & V^*V \end{array} \right),$$

the last expression is equal to

$$\sum_{j=0}^{\infty} \left[\frac{1}{(2j)!} (-1)^{j} \begin{pmatrix} (VV^{*})^{j} & 0 \\ 0 & (V^{*}V)^{j} \end{pmatrix} + \frac{1}{(2j+1)!} (-1)^{j} \begin{pmatrix} (VV^{*})^{j} & 0 \\ 0 & (V^{*}V)^{j} \end{pmatrix} \begin{pmatrix} 0 & V \\ -V^{*} & 0 \end{pmatrix} \right]$$

$$= \sum_{j=0}^{\infty} \left[\frac{1}{(2j)!} (-1)^{j} \begin{pmatrix} (\sqrt{VV^{*}})^{2j} & 0 \\ 0 & (\sqrt{V^{*}V})^{2j} \end{pmatrix} + \frac{1}{(2j+1)!} (-1)^{j} \begin{pmatrix} 0 & (VV^{*})^{j}V \\ -(V^{*}V)^{j}V^{*} & 0 \end{pmatrix} \right].$$

Using (11) and the identities

$$\sum_{j=0}^{\infty} \frac{1}{(2j)!} (-1)^j x^{2j} \equiv \cos x, \quad \sum_{j=0}^{\infty} \frac{1}{(2j+1)!} (-1)^j x^{2j} \equiv \frac{\sin x}{x},$$

and denoting for brevity $\lambda(x) := (\sin x)/x$, we obtain

$$\exp \begin{pmatrix} 0 & V \\ -V^* & 0 \end{pmatrix} = \begin{pmatrix} \cos \sqrt{VV^*} & \lambda(\sqrt{VV^*})V \\ -\lambda(\sqrt{V^*V})V^* & \cos \sqrt{V^*V} \end{pmatrix},$$

where λ ($\sqrt{V^*V}$) denotes the function $(\sin x)/x$ of the operator $\sqrt{V^*V}$. Hence if $p = (X_1, X_2, Y, Z)$, then

$$A_t(p) = (X_1, X_2, \cos(t\sqrt{VV^*})Y + \lambda(t\sqrt{VV^*})tVZ, *),$$

where * denotes some expression, which is irrelevant for us. It follows from this and (10) that

$$r\sqrt{1-r^2}\frac{d}{dt}\varphi(t) = \int_{rS_{X_1,Z}} dX_1 dZ \int_{\sqrt{1-r^2}S_{X_2,Y}} f\left(X_1, X_2, \cos(t\sqrt{VV^*})Y\right) + \lambda(t\sqrt{VV^*})tVZ \langle Y, VZ \rangle dX_2 dY.$$
(12)

We want to show that the expression (12) is nonnegative. Let us fix 0 < t < 1. Since $||V|| \le \pi/2$, the operator $\cos(t\sqrt{VV^*})$ is selfadjoint and invertible. Consider a new smooth function on $L \oplus M \oplus \Delta$:

$$g(X_1, X_2, Y) := f(X_1, X_2, \cos(t\sqrt{VV^*})Y),$$

which is obviously log-concave and even. Consider a selfadjoint operator A: $\Delta \to \Delta$,

(13)
$$A := t \cdot \lambda(t\sqrt{VV^*}) / \cos(t\sqrt{VV^*}).$$

Since $||V|| \le \pi/2$, 0 < t < 1 and

$$\frac{\sin x}{x\cos x} > 0 \quad \text{if } |x| < \frac{\pi}{2},$$

then A > 0. Then the right hand side of (12) can be rewritten

(14)
$$\int_{rS_{X_1,Z}} dX_1 dZ \int_{\sqrt{1-r^2}S_{X_2,Y}} g(X_1, X_2, Y + AVZ) \langle Y, VZ \rangle dX_2 dY.$$

Using the same trick as previously (but now for functions not on the sphere, but on the Euclidean space) and denoting $B_{X_2,Y}$ the unit Euclidean ball in $M \oplus \Delta$, we have for the inner integral in (14)

$$\begin{split} \frac{1}{\sqrt{1-r^2}} \cdot \int\limits_{\sqrt{1-r^2}S_{X_2,Y}} g(X_1,X_2,Y+AVZ)\langle Y,VZ\rangle dX_2 dY \\ (15) &= -\frac{d}{d\tau} \Big|_{\tau=0} \int\limits_{\sqrt{1-r^2}B_{X_2,Y}} g(X_1,X_2,Y+AVZ+\tau VZ) dX_2 dY \\ &= -\frac{d}{d\tau} \Big|_{\tau=0} \int\limits_{\sqrt{1-r^2}B_{X_2,Y}} g(X_1,X_2,A(A^{-1}Y+VZ+\tau A^{-1}VZ)) dX_2 dY \\ &= -\frac{d}{d\tau} \Big|_{\tau=0} \int\limits_{\sqrt{1-r^2}B_{X_2,Y}} h(X_1,X_2,A^{-1}Y+VZ+\tau A^{-1}VZ) dX_2 dY, \end{split}$$

where $h(X_1,X_2,Y)=g(X_1,X_2,AY)$. By (13), A^{-1} can be represented in the form

$$A^{-1} = \sum_{k \ge 0} a_k (VV^*)^k,$$

where a_k are the coefficients in the power series of $\cos(tx)/t \cdot \lambda(tx)$. Thus

$$A^{-1}V = \left(\sum_{k} a_{k} (VV^{*})^{k}\right) V$$

$$= V \sum_{k} a_{k} (V^{*}V)^{k}$$

$$= V \cdot \cos(t\sqrt{V^{*}V}) / t \cdot \lambda(t\sqrt{V^{*}V})$$

$$= V \cdot B,$$
(16)

where B is a selfadjoint positive operator. Define on $L \oplus \Gamma$ a function

(17)
$$\theta(X_1, Z) = \int_{\sqrt{1-r^2}B_{X_2, Y}} h(X_1, X_2, A^{-1}Y + VZ) dX_2 dY.$$

Recall that our theorem would follow from non-negativity of (14). So in this notation we have to prove that

(18)
$$\frac{d}{d\tau}\Big|_{\tau=0} \int_{\tau S_{X_1,Z}} \theta(X_1, Z + \tau BZ) dX_1 dZ \le 0.$$

Since h is log-concave, θ is also log-concave, as follows from the Prekopa-Leindler inequality. Moreover, since h is smooth and even, hence θ is also smooth and even. Then (18) follows from the next lemma.

LEMMA 5: Let θ be a smooth even log-concave function on \mathbb{R}^k . Let $B: \mathbb{R}^k \to \mathbb{R}^k$ be a selfadjoint operator, $B \geq 0$. Then

$$\left. \frac{d}{d\tau} \right|_{\tau=0} \int\limits_{S^{k-1}} \theta(W + \tau BW) dW \le 0.$$

Proof: Observe that

$$\frac{d}{d\tau}\Big|_{\tau=0} \int\limits_{S^{k-1}} \theta(W + \tau BW) dW = \frac{d}{d\tau}\Big|_{\tau=0} \int\limits_{S^{k-1}} \theta(e^{\tau B}W) dW.$$

It remains to check that the function of τ ,

$$\int_{S^{k-1}} \theta(e^{\tau B}W)dW,$$

decreases. Every even log-concave function can be approximated by a linear combination with positive coefficients of characteristic functions of convex centrally symmetric sets. Let K be such a set $\mathbb{1}_K$ be its characteristic function. Then

$$\int_{S^{k-1}} 1\!\!1_K(e^{\tau B}W)dW = \int_{S^{k-1}} 1\!\!1_{e^{-\tau B}K}(W)dW = \operatorname{mes}(S^{k-1} \cap e^{-\tau B}K).$$

Since $B \ge 0$, then $e^{-\tau B}$ is a contraction, i.e. $||e^{-\tau B}|| \le 1$.

Now the lemma follows from the result of [2], which states that if K is a centrally symmetric convex body, $C: \mathbb{R}^k \longrightarrow \mathbb{R}^k$ a contraction, then

$$\operatorname{mes}(S^{k-1} \cap CK) \le \operatorname{mes}(S^{k-1} \cap K). \quad \blacksquare$$

ACKNOWLEDGEMENT: We are grateful to Professor E. D. Gluskin for drawing our attention to the problem and for very helpful discussions. We thank A. Litvak, Professor V. D. Milman and B. Sudakov for fruitful discussions and the referee for very useful suggestions. Thus in the preliminary version of the paper Theorem 1 was proved under an additional assumption on the dimensions of the D and Ω . It was kindly mentioned to us by the referee that this assumption can be removed with a minor change in the proof.

References

- [1] J. Cheeger and D. G. Ebin, Comparison Theorems in Riemannian Geometry, North-Holland, Amsterdam, 1975.
- [2] C. Fefferman, M. Jodeit and M. D. Perlman, A spherical surface area measure inequality for convex sets, Proceedings of the American Mathematical Society 33 (1972), 114–119.
- [3] E. D. Gluskin, Extremal properties of orthogonal parallelepipeds and their applications to the geometry of Banach space, Mathematics of the USSR-Sbornik 64 (1989), 85–96.
- [4] E. D. Gluskin, On the stability of volume radius, preprint.
- [5] M. Gromov, Monotonicity of the volume of intersection of balls, in Geometric Aspects of Functional Analysis, Israel Seminar 1985–86 (J. Lindenstrauss and V. D. Milman, eds.), Lecture Notes in Mathematics 1267, Springer-Verlag, Berlin, 1987, pp. 1–4.
- [6] L. D. Ivanov, Variations of Sets and Functions, Nauka, Moscow, 1975 (in Russian).
- [7] C. G. Khatri, On certain inequalities of normal distributions and their applications to simultaneous confidence bounds, Annals of Mathematical Statistics 38 (1967), 1853–1867.
- [8] A. Litvak, V. D. Milman and G. Schechtman, Averages of norms and behavior of families of projective caps on the sphere, Comptes Rendus de l'Académie des Sciences, Paris 325, Série I (1997), 289-294.
- [9] Z. Sidak, Rectangular confidence regions for the means of multivariate normal distributions, Journal of the American Statistical Association 62 (1967), 626-633.